

DOI <https://doi.org/10.24297/jam.v19i.8885>**On the solvability of a nonlinear functional integral equations via measure of noncompactness in $L^p(\mathbb{R}^N)$** *Wagdy G. El-Sayed¹, Mahmoud M. El-Borai², Mohamed M.A. Metwali³, Nagwa I. Shemais⁴*^{1,2}Faculty of Science, Alexandria University, Alexandria, Egypt^{3,4}Department of mathematics, Faculty of Science, Damanhour University, Egypt¹wagdygoma@alexu.edu.eg, ²m_m_elborai@yahoo.com, ³m.metwali@yahoo.com, ⁴n.ibrahim90@yahoo.com**Abstract**

Using the technique of a suitable measure of non-compactness and the Darbo fixed point theorem, we investigate the existence of a nonlinear functional integral equation of Urysohn type in the space of Lebesgue integrable functions $L^p(\mathbb{R}^N)$. In this space, we show that our functional-integral equation has at least one solution. Finally an example is also discussed to indicate the natural realizations of our abstract result.

Keywords: functional integral equation; measure of noncompactness; existence; Darbo's fixed point theorem; fixed point.

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1 Introduction

Integral equations appear in many applications in describing numerous real world problems (see, for instance, ([30], [31], [5], [18]), and references therein).

Also many useful applications in describing problems of the real world and numerous events, which appear in physics, engineering, mechanics, biology, etc. See for example [1, 4, 8, 13, 15] can be depicted and demonstrated by methods of non-linear functional integral equations (for example, we refer to [25, 26, 28]). Apart from that, integral equations are often investigated in research papers and monographs (cf. [6, 12, 16, 18, 29, 32]) and the references cited therein.

2 Preliminaries

We will collect in this section some definitions and basic results which will be used further on throughout the paper.

First, we denote $L^p(U)$ ($U \in \mathbb{R}^N$) as the space of Lebesgue integrable functions on U with the standard norm

$$\|x\|_{L^p(U)} = \left(\int_U |x(t)|^p dt \right)^{\frac{1}{p}}.$$

Theorem 2.1 [1, 8, 9]

Let F be a bounded set in $L^p(\mathbb{R}^N)$ with $1 \leq p < \infty$. The closure of F in $L^p(\mathbb{R}^N)$ is compact if and only if

$$\lim_{h \rightarrow 0} \|\tau_h f - f\|_{L^p(\mathbb{R}^N)} = 0 \quad \text{uniformly in } f \in F,$$

where $\tau_h f(x) = f(x+h)$ for all $x, h \in \mathbb{R}^N$. Also for $\epsilon > 0$ there is a bounded and measurable subset $\Omega \subset (\mathbb{R}^N)$ such that

$$\|f\|_{(L^p(\mathbb{R}^N \setminus \Omega))} < \epsilon \quad \text{for all } f \in F.$$

Next, we recall the concept of measure of noncompactness, let E be an infinite dimensional Banach space with norm $\|\cdot\|$ and zero element θ . Denote by \mathcal{M}_E the family of all nonempty and bounded subsets of E , \mathcal{N}_E and \mathcal{N}_E^W

the family of all nonempty relatively compact

and weakly relatively compact sets, respectively. The symbols \bar{X} and $\text{Conv}X$ stand for the closure and closed convex hull of a subset X of E , respectively. We use the standard notation $X+Y$ and λX for algebraic operations on sets,

while,

we denote $B_r = B(\theta, r)$ the closed ball centered at θ and with radius r .

Definition 2.1 (Measure of noncompactness)

[12]

A mapping $\mu : \mathcal{M}_E \rightarrow [0, \infty)$ is said to be a measure of noncompactness in E if it satisfies the following conditions:

- (1) the family $\ker\mu = \{X \in \mathcal{M}_E : \mu(X) = 0\}$ is nonempty and $\ker\mu \subset \mathcal{N}_E$, where $\ker\mu$ is called the kernel of the measure μ .
- (2) $X \subset Y \Rightarrow \mu(X) \leq \mu(Y)$.
- (3) $\mu(\text{Conv}X) = \mu(X) = \mu(\overline{X})$.
- (4) $\mu[\lambda X + (1 - \lambda)Y] \leq \lambda\mu(X) + (1 - \lambda)\mu(Y)$, $\lambda \in [0, 1]$.
- (5) If $X_n \in \mathcal{M}_E$, $X_n = \overline{X_n}$ and $X_{n+1} \subset X_n$ for $n = 1, 2, \dots$ and if

$\lim_{n \rightarrow \infty} \mu(X_n) = 0$, then

$$X_\infty = \bigcap_{n=1}^\infty X_n \neq \phi.$$

Theorem 2.2 [1]

Suppose $1 \leq p < \infty$ and X is a bounded subset of (\mathbb{R}^N) . For $x \in X$ and $\epsilon > 0$

$$w^T(x, \epsilon) = \sup\{\|\tau_h x - x\|_{L^p(B_T)} : \|h\|_{\mathbb{R}^N} < \epsilon\},$$

$$w^T(X, \epsilon) = \sup\{w^T(x, \epsilon) : x \in X\},$$

$$w^T(X) = \lim_{\epsilon \rightarrow 0} w^T(X, \epsilon),$$

$$w(X) = \lim_{T \rightarrow \infty} w^T(X),$$

$$d(X) = \lim_{T \rightarrow \infty} \sup\{\|x\|_{L^p(\mathbb{R}^N \setminus B_T)} : x \in X\},$$

where $B_T = \{a \in \mathbb{R}^N : \|a\|_{\mathbb{R}^N} \leq T\}$. Then

$$\mu(X) = w(X) + d(X)$$

is a measure of non compactness on $L^p(\mathbb{R}^N)$.

At the end of this section, we recall the fixed point theorem due to Darbo which enables us to prove the existence theorem for solutions of a several integral equations considered in nonlinear analysis. To quote this theorem we need the following definitions.

Definition 2.2 [12]

The function $f : I \times \mathbb{R} \rightarrow \mathbb{R}$ satisfies Carathéodory condition if it satisfies the following two conditions:

- (1) f is measurable in $t \in I$ for any $x \in \mathbb{R}$.
- (2) f is continuous in $x \in \mathbb{R}$ for almost all $t \in I$.

Definition 2.3 (Darbo condition)[11]

Let Ω be a nonempty subset of a Banach space E and let $A : \Omega \rightarrow E$ be a continuous operator which transforms bounded sets onto bounded ones. We say that A satisfies the Darbo condition (with a constant $k \geq 0$) with respect to a measure of noncompactness μ if for any bounded subset X of

Ω , we have $\mu(AX) \leq k\mu(X)$.

Note that, if A satisfies the Darbo condition with $k < 1$, then it is called a contraction operator with respect to μ .

Theorem 2.3 (Darbo fixed point theorem)[7]

Let Ω be a nonempty, bounded, closed and convex subset of E and let $f : \Omega \rightarrow \Omega$ be a continuous transformation which is a contraction with respect to the measure of noncompactness μ , i.e. there exists a constant $k \in [0, 1)$ such that

$$\mu(fX) \leq k\mu(X),$$

for any nonempty subset X of Ω . Then f has at least one fixed point in the set Ω .

3 Main result

This section is devoted to discuss the solvability of the following nonlinear functional integral equation

$$u(x) = f(x) + g_1(x, u(x)) + h_1 \left(x, g_2(x, u(x)), \int_{\mathbb{R}^N} h_2(x, y, (Qu)(y)) dy \right). \quad (1)$$

Now, we will try to assume some assumptions under which we can prove our existence theorem.

Assume the following conditions are satisfied:

- (i) $f \in L^p(\mathbb{R}^N)$;
- (ii) $g_i : \mathbb{R}^N \times \mathbb{R} \rightarrow \mathbb{R}$ satisfy Carathéodory condition (i.e. measurable in t for all $x \in \mathbb{R}^N$, and continuous in x for all $t \in \mathbb{R}$) and there exists a constant $l \in [0, 1)$ and $a_i \in L^p(\mathbb{R}^N)$ such that

$$|g_i(x, u) - g_i(y, v)| \leq |a_i(x) - a_i(y)| + l|u - v|,$$

for any $u, v \in \mathbb{R}$ and almost all $x, y \in \mathbb{R}^N$ where $i = 1, 2$.

(iii) $h_1 : \mathbb{R}^N \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$ such that

$$|h_1(x, y, z)| \leq a(x, y) + b_1|z|,$$

for all $x, y \in \mathbb{R}^N, a \in L^q(\mathbb{R}^N)$, where $|a(x, y)| \leq a_3(x) + b_2|y|$ where $b_1, b_2 \geq 0$ are constant and $a_3 \in L^q(\mathbb{R}^N)$.

(iv) $|h_2(x, y, u)| \leq k(x, y)\{a_4(y) + b|u|\}$, where $h_2 : \mathbb{R}^N \times \mathbb{R}^N \times \mathbb{R} \rightarrow \mathbb{R}, b > 0, a_4 \in L^p(\mathbb{R}^N)$ and $k(x, y)$ satisfies Carathéodory condition $k : \mathbb{R}^N \times \mathbb{R}^N \rightarrow \mathbb{R}$ and there exist f

$f_1, f_2 \in L^p(\mathbb{R}^N)$ and $f^* \in L^q(\mathbb{R}^N)$ ($\frac{1}{p} + \frac{1}{q} = 1$) such that $|k(x, y)| \leq f^*(y)f_1(x)$, for all $x, y \in \mathbb{R}^N$ and

$$|k(x_1, y) - k(x_2, y)| \leq f^*(y)|f_2(x_1) - f_2(x_2)|.$$

(v) The operator Q is bounded linear operator and continuously maps the space $L^p(\mathbb{R}^N)$ into itself. Moreover, there exists a nondecreasing function $\psi : \mathbb{R}_+ \rightarrow \mathbb{R}_+$ such that

$$\|Qu\|_{L^p(\mathbb{R}^N)} \leq \psi(\|u\|_{L^p(\mathbb{R}^N)})$$

for any $u \in L^p(\mathbb{R}^N)$.

(vi) there exists a positive constant r_0 such that

$$\begin{aligned} & \|f\|_{L^p(\mathbb{R}^N)} + lr_0 + \|g_1(x, 0)\|_{L^p(\mathbb{R}^N)} + \|a_3\|_{L^p(\mathbb{R}^N)} + b_2lr_0 \\ & + b_2\|g_2(x, 0)\|_{L^p(\mathbb{R}^N)} + b_1\|K\|_1\|a_4\|_{L^p(\mathbb{R}^N)} + bb_1\|K\|_1\psi(r_0) \end{aligned}$$

$\leq r_0$, where

$$(Ku)(t) = \int_{\mathbb{R}^N} k(x, y)u(y)dy$$

and

$$\|K\|_1 = \{Sup\|Ku\|_{L^p(\mathbb{R}^N)} : \|u\| \leq r\}$$

0}.

Remark 3.1 The linear fredholm integral operator $K : L^p(\mathbb{R}^N) \rightarrow L^p(\mathbb{R}^N)$ is a continuous operator and $\|K\|_1 \leq \infty$.

Theorem 3.1 If the above assumptions (i)-(vi) are satisfied then the functional integral equation 1 has at least one solution in $L^p(\mathbb{R}^N)$.

Proof: First of all, we define the operator $F : L^p(\mathbb{R}^N) \rightarrow L^p(\mathbb{R}^N)$ by

$$(Fu)(x) = f(x) + g_1(x, u(x)) + h_1\left(x, g_2(x, u(x)), \int_{\mathbb{R}^N} h_2(x, y, (Qu)(y))dy\right),$$

and $(GU)(x) = h_1\left(x, g_2(x, u(x)), \int_{\mathbb{R}^N} h_2(x, y, (Qu)(y))dy\right)$. Now Fu is measurable for any $u \in L^p(\mathbb{R}^N)$, we will prove that $Fu \in L^p(\mathbb{R}^N)$ for any $u \in L^p(\mathbb{R}^N)$ as $G : L^p(\mathbb{R}^N) \rightarrow L^p(\mathbb{R}^N)$ using the above conditions, we have the following inequality

$$|(Gu)(x)| = |h_1\left(x, g_2(x, u(x)), \int_{\mathbb{R}^N} h_2(x, y, (Qu)(y))dy\right)|$$

$$\begin{aligned}
 &\leq a(x, g_2(x, u(x))) + b_1 \left| \int_{\mathbb{R}^N} h_2(x, y, (Qu)(y)) dy \right| \\
 &\leq a_3(x) + b_2 |g_2(x, u(x))| + b_1 \int_{\mathbb{R}^N} |h_2(x, y, (Qu)(y))| dy \\
 &\leq a_3(x) + b_2 |g_2(x, u(x)) - g_2(x, 0)| + b_2 |g_2(x, 0)| \\
 &\quad + b_1 \int_{\mathbb{R}^N} k(x, y) [a_4(y) + b |(Qu)(y)|] dy \\
 &\leq a_3(x) + b_2 |a_2(x) - a_2(x)| + b_2 l |u| + b_2 |g_2(x, 0)| \\
 &\quad + b_1 \int_{\mathbb{R}^N} k(x, y) a_4(y) dy + b b_1 \int_{\mathbb{R}^N} k(x, y) |(Qu)(y)| dy \\
 &\leq a_3(x) + b_2 l |u| + b_2 |g_2(x, 0)| + b_1 \int_{\mathbb{R}^N} k(x, y) a_4(y) dy \\
 &\quad + b b_1 \int_{\mathbb{R}^N} k(x, y) |(Qu)(y)| dy, \\
 &\|Gu\|_{L^p(\mathbb{R}^N)} \leq \|a_3\|_{L^p(\mathbb{R}^N)} + b_2 l \|u\|_{L^p(\mathbb{R}^N)} + b_2 \|g_2(x, 0)\|_{L^p(\mathbb{R}^N)} \\
 &\quad + b_1 \|K\|_1 \|a_4\|_{L^p(\mathbb{R}^N)} + b b_1 \|K\|_1 \|Qu\|_{L^p(\mathbb{R}^N)} \\
 &< \infty,
 \end{aligned}$$

then from assumptions (i), (ii), $F(u) \in L^p(\mathbb{R}^N)$ and F is will defined

$$\begin{aligned}
 &|(Fu)(x)| \leq |f(x)| + \\
 &|g_1(x, u(x))| + |Gx| \\
 &\leq |f(x)| + l |u| + |g_1(x, 0)| + |Gx| \\
 &\|Fu\|_{L^p(\mathbb{R}^N)} \leq \|f\|_{L^p(\mathbb{R}^N)} + l \|u\|_{L^p(\mathbb{R}^N)} + \|g_1(x, 0)\|_{L^p(\mathbb{R}^N)} + \|G\|_{L^p(\mathbb{R}^N)} \\
 &\leq \|f\|_{L^p(\mathbb{R}^N)} + l \|u\|_{L^p(\mathbb{R}^N)} + \|g_1(x, 0)\|_{L^p(\mathbb{R}^N)} + \|a_3\|_{L^p(\mathbb{R}^N)} \\
 &\quad + b_2 l \|u\|_{L^p(\mathbb{R}^N)} + b_2 \|g_2(x, 0)\|_{L^p(\mathbb{R}^N)} \\
 &\quad + b_1 \|K\|_1 \|a_4\|_{L^p(\mathbb{R}^N)} + b b_1 \|K\|_1 \|Qu\|_{L^p(\mathbb{R}^N)} \\
 &< \infty.
 \end{aligned}$$

Next, we show that

$F : B_{r_0} \rightarrow B_{r_0}$ where

B_{r_0} is closed ball of radius r_0 is constant, let $u \in B_{r_0}$ where ($\| u \| \leq r_0$)

$$\begin{aligned} \| Fu \|_{L^p(\mathbb{R}^N)} &\leq \| f \|_{L^p(\mathbb{R}^N)} + lr_0 + \| g_1(x, 0) \|_{L^p(\mathbb{R}^N)} + \| a_3 \|_{L^p(\mathbb{R}^N)} + b_2lr_0 \\ &+ b_2 \| g_2(x, 0) \|_{L^p(\mathbb{R}^N)} + b_1 \| K \|_1 \| a_4 \|_{L^p(\mathbb{R}^N)} \\ &+ bb_1 \| K \|_1 \psi(r_0) \end{aligned}$$

$\leq r_0$.

Now, we show that $w_0(FX) \leq l(b_2 + 1)w_0(X)$ for any nonempty set $X \subset B_{r_0}$. To do this, we fix arbitrary $T > 0$ and $\epsilon > 0$, let us choose $u \in X$ and for $x, h \in B_T$ with $\| h \|_{\mathbb{R}^N} \leq \epsilon$, we have

$$\begin{aligned} &|(Gu)(x+h)-(Gu)(x)| \\ &= \left| h_1(x+h, g_2(x+h, u(x+h)), \int_{\mathbb{R}^N} h_2(x+h, y, (Qu)(y))dy) \right. \\ &- \left. h_1(x, g_2(x, u(x)), \int_{\mathbb{R}^N} h_2(x, y, (Qu)(y))dy) \right| \\ &\leq |a_3(x+h) + b_2 |g_2(x+h, u(x+h))| - a_3(x) - b_2 |g_2(x, u(x))| \\ &+ b_1(|\int_{\mathbb{R}^N} h_2(x+h, y, (Qu)(y))dy| - |\int_{\mathbb{R}^N} h_2(x, y, (Qu)(y))dy|) \\ &\leq |a_3(x+h) - a_3(x)| + b_2 |g_2(x+h, u(x+h)) - g_2(x, u(x))| \\ &+ b_1 \left(\int_{\mathbb{R}^N} k(x+h, y)[a_4(y) + b |(Qu)(y)|]dy \right. \\ &- \left. \int_{\mathbb{R}^N} k(x, y) \right. \\ &\times \left. [a_4(y) + b |(Qu)(y)|]dy \right) \\ &\leq |a_3(x+h) - a_3(x)| + b_2 |g_2(x+h, u(x+h)) - g_2(x, u(x))| \\ &+ b_1 \left(\int_{\mathbb{R}^N} |k(x+h, y) - k(x, y)| [a_4(y) + b |(Qu)(y)|]dy \right) \\ &\leq |a_3(x+h) - a_3(x)| + b_2 |g_2(x+h, u(x+h)) - g_2(x+h, u(x))| \\ &+ b_2 |g_2(x+h, u(x)) - g_2(x, u(x))| + b_1 \int_{\mathbb{R}^N} f^*(y)(|f_2(x+h) - f_2(x)|) \\ &\times [a_4(y) + b |(Qu)(y)|]dy \\ &\leq |a_3(x+h) - a_3(x)| + b_2l |u(x+h) - u(x)| + b_2(|a_2(x+h) - a_2(x)| \\ &+ b_2l |u(x) - u(x)|) + b_1 \int_{\mathbb{R}^N} f^*(y) |f_2(x+h) - f_2(x)| a_4(y)dy \\ &+ b b_1 \int_{\mathbb{R}^N} f^*(y) |f_2(x+h) - f_2(x)| |(Qu)(y)| dy. \end{aligned}$$

$$\begin{aligned} & \|\tau_h Gu - Gu\|_{L^p} = \left(\int_{B^T} |(Gu)(x+h) - (Gu)(x)|^p dx \right)^{\frac{1}{p}} \\ & \leq \left(\int_{B^T} |a_3(x+h) - a_3(x)|^p dx \right)^{\frac{1}{p}} + lb_2 \left(\int_{B^T} |u(x+h) - u(x)|^p dx \right)^{\frac{1}{p}} \\ & + \left(\int_{B^T} b_2 |a_2(x+h) - a_2(x)|^p dx \right)^{\frac{1}{p}} \\ & + b_1 \\ & \left[\int_{B^T} \left(\int_{\mathbb{R}^N} |f^*(y)|^q a_4(y) |f_2(x+h) - f_2(x)|^q |a_2(y)|^q dy \right)^{\frac{p}{q}} dx \right]^{\frac{1}{p}} \\ & + bb_1 \left[\int_{B^T} \left(\int_{\mathbb{R}^N} |f^*(y)|^q |f_2(x+h) - f_2(x)|^q |(Qu)(y)|^q dy \right)^{\frac{p}{q}} dx \right]^{\frac{1}{p}} \end{aligned}$$

$$\begin{aligned} & \|\tau_h Gu - Gu\|_{L^p} \\ & \leq \|\tau_h a_3 - a_3\|_{L^p(B^T)} + lb_2 \|\tau_h u - u\|_{L^p(B^T)} + b_2 \|\tau_h a_2 - a_2\|_{L^p(B^T)} \\ & + b_1 \|f^*\|_{L^q(\mathbb{R}^N)} \\ & \times \|\tau_h f_2 - f_2\|_{L^p(B^T)} \|a_4\|_{L^p(\mathbb{R}^N)} \\ & + b b_1 \|f^*\|_{L^q(\mathbb{R}^N)} \\ & \|Qu\|_{L^p(\mathbb{R}^N)} \\ & \leq w^T(a_3, \epsilon) + lb_2 w^T(u, \epsilon) + b_2 w^T(a_2, \epsilon) \\ & + b_1 w^T(f_2, \epsilon) \|f^*\|_{L^q(\mathbb{R}^N)} \|a_4\|_{L^p(\mathbb{R}^N)} + bb_1 \|f^*\|_{L^q(\mathbb{R}^N)} \\ & w^T(f_2, \epsilon) \psi(\|u\|)_{L^p(\mathbb{R}^N)}. \end{aligned}$$

$$|(Fu)(x+h) - (Fu)(x)|$$

$$\begin{aligned}
 &\leq |f(x+h) - f(x)| + |g_1(x+h, u(x+h)) - g_1(x, u(x))| \\
 &+ |(Gu)(x+h) - (Gu)(x)| \\
 &\leq |f(x+h) - f(x)| + |g_1(x+h, u(x+h)) - g_1(x+h, u(x))| \\
 &+ |g_1(x+h, u(x)) - g(x, u(x))| + |(Gu)(x+h) - (Gu)(x)| \\
 &\leq |f(x+h) - f(x)| + |a_1(x+h) - a_1(x)| + l|u(x+h) - u(x)| \\
 &+ |(Gu)(x+h) - (Gu)(x)| \\
 &\|\tau_h Fu - Fu\|_{L^p} \leq \left(\int_{B^T} |f(x+h) - f(x)|^p dx\right)^{\frac{1}{p}} + l\left(\int_{B^T} |u(x+h) - u(x)|^p dx\right)^{\frac{1}{p}} \\
 &+ \\
 &\left(\int_{B^T} |a_1(x+h) - a_1(x)|^p dx\right)^{\frac{1}{p}} + \|\tau_h Gu - Gu\|_{L^p(B^T)} \\
 &\leq \|\tau_h f - f\|_{L^p(B^T)} + l\|\tau_h u - u\|_{L^p(B^T)} + \|\tau_h a_1 - a_1\|_{L^p(B^T)} \\
 &+ \|\tau_h G - G\|_{L^p(B^T)},
 \end{aligned}$$

$$\begin{aligned}
 w^T(FX, \epsilon) &\leq w^T(f, \epsilon) + lw^T(u, \epsilon) + w^T(a_1, \epsilon) + w^T(a_3, \epsilon) + lb_2w^T(u, \epsilon) \\
 &+ w^T(a_2, \epsilon) + b_1w^T(f_2, \epsilon)\|f^*\|_{L_q(\mathbb{R}^N)}\|a_4\|_{L_p(\mathbb{R}^N)} \\
 &+ bb_1\|f^*\|_{L_q(\mathbb{R}^N)}
 \end{aligned}$$

$$w^T(f_2, \epsilon)\psi(\|u\|)_{L_p(\mathbb{R}^N)}.$$

Thus, we obtain

$$\begin{aligned}
 w^T(FX, \epsilon) &\leq w^T(f, \epsilon) + lw^T(X, \epsilon) + w^T(a_1, \epsilon) + w^T(a_3, \epsilon) + lb_2w^T(u, \epsilon) \\
 &+ w^T(a_2, \epsilon) + b_1w^T(f_2, \epsilon)\|f^*\|_{L_q(\mathbb{R}^N)}\|a_4\|_{L_p(\mathbb{R}^N)} \\
 &+ bb_1\|f^*\|_{L_q(\mathbb{R}^N)}
 \end{aligned}$$

$$w^T(f_2, \epsilon)\psi(r_0).$$

Also, we have $w^T(f_2, \epsilon)$, $w^T(f, \epsilon)$, and $w^T(a_i, \epsilon) \rightarrow 0$ as $\epsilon \rightarrow \infty$ where $i = 1, 2, 3$

then, we obtain

$$w(FX) \leq l(b_2 + 1)w(X), \quad \text{where } l(b_2 + 1) \leq 1. \tag{-13}$$

Next, let us fix an arbitrary number $T > 0$, then taking into account our assumptions, for an arbitrary function $u \in X$. We have

$$\begin{aligned}
 & \left(\int_{\mathbb{R}^N} \chi_{B^T} |(Fu)(x)|^p dx \right)^{\frac{1}{p}} \leq \left(\int_{\mathbb{R}^N \setminus B^T} |f(x)|^p dx \right)^{\frac{1}{p}} + \left(\int_{\mathbb{R}^N \setminus B^T} |g_1(x, u(x))|^p dx \right)^{\frac{1}{p}} \\
 & + \left(\int_{\mathbb{R}^N \setminus B^T} \left| h_1(x, g_2(x, u(x)), \int_{\mathbb{R}^N} h_2(x, y, (Qu)(y)) dy) \right|^p dx \right)^{\frac{1}{p}} \\
 & \leq \left(\int_{\mathbb{R}^N \setminus B^T} |f(x)|^p dx \right)^{\frac{1}{p}} + \left(\int_{\mathbb{R}^N \setminus B^T} |g_1(x, u(x)) - g_1(x, 0)|^p dx \right)^{\frac{1}{p}} \\
 & + \left(\int_{\mathbb{R}^N \setminus B^T} |g_1(x, 0)|^p dx \right)^{\frac{1}{p}} \\
 & + \left(\int_{\mathbb{R}^N \setminus B^T} |a_3(x) + b_2 |g_2(x, u(x))| + b_1 \int_{\mathbb{R}^N} |h_2(x, y, (Qu)(y)) dy| \right)^p dx \right)^{\frac{1}{p}} \\
 & \leq \left(\int_{\mathbb{R}^N \setminus B^T} |f(x)|^p dx \right)^{\frac{1}{p}} + l \left(\int_{\mathbb{R}^N \setminus B^T} |u(x)|^p dx \right)^{\frac{1}{p}} + \left(\int_{\mathbb{R}^N \setminus B^T} |g_1(x, 0)|^p dx \right)^{\frac{1}{p}} \\
 & + \left(\int_{\mathbb{R}^N \setminus B^T} |a_3(x)|^p dx \right)^{\frac{1}{p}} + b_2 l \left(\int_{\mathbb{R}^N \setminus B^T} |u(x)|^p dx \right)^{\frac{1}{p}} + b_2 \left(\int_{\mathbb{R}^N \setminus B^T} |g_2(x, 0)|^p dx \right)^{\frac{1}{p}} \\
 & + \\
 & b_1 \left(\int_{\mathbb{R}^N \setminus B^T} \left(\int_{\mathbb{R}^N} |k(x, y)| \times [a_4(y) + b|(Qu)(y)|] dy \right)^p dx \right)^{\frac{1}{p}} \\
 & \leq \left(\int_{\mathbb{R}^N \setminus B^T} |f(x)|^p dx \right)^{\frac{1}{p}} + l \left(\int_{\mathbb{R}^N \setminus B^T} |u(x)|^p dx \right)^{\frac{1}{p}} + \left(\int_{\mathbb{R}^N \setminus B^T} |g_1(x, 0)|^p dx \right)^{\frac{1}{p}} \\
 & + \left(\int_{\mathbb{R}^N \setminus B^T} |a_3(x)|^p dx \right)^{\frac{1}{p}} + b_2 l \left(\int_{\mathbb{R}^N \setminus B^T} |u(x)|^p dx \right)^{\frac{1}{p}} \\
 & + b_2 \left(\int_{\mathbb{R}^N \setminus B^T} |g_2(x, 0)|^p dx \right)^{\frac{1}{p}} + b_1 \left(\int_{\mathbb{R}^N \setminus B^T} \left(\int_{\mathbb{R}^N} |k(x, y)|^q |a_4(y)|^q dy \right)^{\frac{p}{q}} dx \right)^{\frac{1}{p}}
 \end{aligned}$$

$$\begin{aligned}
 & + bb_1 \left(\int_{\mathbb{R}^N \setminus B^T} \left(\int_{\mathbb{R}^N} |k(x, y)|^q |(Qu)(y)|^q dy \right)^{\frac{p}{q}} dx \right)^{\frac{1}{p}} \\
 & \leq \|f\|_{L^p(\mathbb{R}^N \setminus B^T)} + l \|u\|_{L^p(\mathbb{R}^N \setminus B^T)} + \|g_1(\cdot, 0)\|_{L^p(\mathbb{R}^N \setminus B^T)} \\
 & + \|a_3\|_{L^p(\mathbb{R}^N \setminus B^T)} + b_2 l \|u\|_{L^p(\mathbb{R}^N \setminus B^T)} + b_2 \|g_2(\cdot, 0)\|_{L^p(\mathbb{R}^N \setminus B^T)} \\
 & + b_1 \\
 & \|f^*\|_{L^q(\mathbb{R}^N)} \cdot \|f_1\|_{L^p(\mathbb{R}^N \setminus B^T)} \cdot (\|a_4\|_{L^p(\mathbb{R}^N \setminus B^T)} + b\psi(\|u\|)_{L^p(\mathbb{R}^N)}).
 \end{aligned}$$

Also we have $\|f\|_{L^p(\mathbb{R}^N \setminus B^T)}, \|g_i(\cdot, 0)\|_{L^p(\mathbb{R}^N \setminus B^T)}, \|f_1\|_{L^p(\mathbb{R}^N \setminus B^T)}, \|a_3\|_{L^p(\mathbb{R}^N \setminus B^T)} \rightarrow 0$

as $T \rightarrow \infty$ where $i = 1, 2$
and hence we obtain that

$$d(FX) \leq l(b_2 + 1)d(X). \tag{-16}$$

Consequently we infer from equation -13, -16

$$w_0(FX) \leq l(b_2 + 1)w_0(X),$$

so, the operator F satisfies all conditions of Darbo fixed point theorem, which enables us to deduce that F has at least one solution in $L^p(\mathbb{R}^N)$. Thus the proof is finished.

Next, we will need the following theorem that help us in a coming example.

Theorem 3.2 [4]

Let $\Omega \subseteq \mathbb{R}^N$ be a measure space and suppose $k : \Omega \times \Omega \rightarrow \mathbb{R}$ is a measurable function for which there is constant $C > 0$ such that

$$\int_I |k(x, y)| dx \leq C \quad \text{a.e. } y \in \Omega$$

and

$$\int_I |k(x, y)| dy \leq C \quad \text{a.e. } x \in \Omega.$$

If $K : L^p(\Omega)$

$\rightarrow L^p(\Omega)$ is defined by

$$(Kf)(x) = \int_{\Omega} f(y) dy,$$

then K is a bounded and continuous operator and $\|K\|_1 \leq C$.

Example: consider the integral equation

$$\int_{\mathbb{R}^2} \frac{y_2}{1+y_1^2+2e^{-|u(x)|}u(x)} dx,$$

where

$$x = (x_1, x_2) \in \mathbb{R}^2,$$

and $\|x\|$ is the Euclidean norm. We study the solvability of this integral equation in the space $L^p(\mathbb{R}^2)$ for $p, q > 2$.

Let $f(x) = e^{-x^2}$, $g_1(x, u(x)) = \frac{\sin u}{\|x\|+4}$,

$$h_2(x, y, (Qu)(y)) = \frac{e^{-(|x_1|+|y_1|)}}{(|x_2|+3)^2(|y_2|+2)^2} \left(\frac{y_2}{1+y_1^2} + 2e^{-|u(x)|}u(x) \right),$$

$$a(x, y) = e^{-x^2} + \frac{\sin u}{\|x\|+4} \text{ with } b_1 = \frac{1}{8}, a_3(x) = e^{-x^2} \text{ where } a_3 \in L^p(\mathbb{R}^2) \text{ such that } b_2 = 1, g_2(x, u(x)) = \frac{\sin u}{\|x\|+4}.$$

Hence the norm

$$\|f\|_{L^p(\mathbb{R}^2)} = \left(\frac{\pi}{p}\right)^{\frac{1}{p}}.$$

Next the functions $g_i(x, u(x)), i = 1, 2$ satisfy the assumption(ii) with $a_i(x) = \frac{1}{\|x\|+4}, l = \frac{1}{4}$, indeed

$$\begin{aligned} |g_i(x, u) - g_i(y, v)| &= \left| \frac{\sin u}{\|x\|+4} - \frac{\sin v}{\|y\|+4} \right| \\ &\leq \left| \frac{1}{\|x\|+4} - \frac{1}{\|y\|+4} \right| |\sin u| + \frac{1}{\|y\|+4} |\sin u - \sin v| \\ &\leq \left| \frac{1}{\|x\|+4} - \frac{1}{\|y\|+4} \right| + \frac{1}{4} |u - v| \\ &= |a_i(x) - a_i(y)| + l |u - v| \end{aligned}$$

where $a_i(x) \in L_p(\mathbb{R}^2)$ with norm

$$\|a_i\|_{L^p(\mathbb{R}^2)} = \left(\frac{4\pi(2)^{1-p}}{(p-1)(p-2)} \right)^{\frac{1}{p}},$$

where $a_4 = \frac{y_2}{1+y_1^2}$, with $\|a_4\|_{L^p(\mathbb{R}^2)} = 0$, also

$$k(x, y) = \frac{e^{-(|x_1|+|y_1|)}}{(|x_2|+3)^2(|y_2|+2)^2},$$

$f^*(x) = \frac{e^{-|x_1|}}{(|x_2|+3)^2}, f_1(x) = f_2(x) = \frac{e^{-(|x_1|)}}{(|x_2|+2)^2}$ we see that $f_1, f_2 \in L_p(\mathbb{R}^2), f^* \in L_q(\mathbb{R}^2)$. Also we have

$$\int_{\mathbb{R}^2} |k(x, y)| dx = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \frac{e^{-(|x_1|+|y_1|)}}{(|x_2|+3)^2(|y_2|+2)^2} dx_1 dx_2 \leq \frac{1}{3},$$

$$\int_{\mathbb{R}^2} |k(x, y)| dy = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \frac{e^{-(|x_1|+|y_1|)}}{(|x_2|+3)^2(|y_2|+2)^2} dy_1 dy_2 \leq \frac{2}{9},$$

and thus from the theorem $\|K\|_1 \leq \frac{1}{3}$ furthermore $b = 2$, $Q(u)(x) = e^{-|u(x)|}u(x)$ satisfies the assumption with $\psi(t) = t$. Finally, the inequality from assumption (vi) has the form

$$\begin{aligned} & \|f\|_{L_p(\mathbb{R}^2)} + lr_0 + \|g_1(x, 0)\|_{L_p(\mathbb{R}^2)} + \|a_3\|_{L_p(\mathbb{R}^2)} + b_2lr_0 \\ & + b_2 \|g_2(x, 0)\|_{L_p(\mathbb{R}^2)} + b_1 \|K\|_1 \|a_4\|_{L_p(\mathbb{R}^2)} + bb_1 \|K\|_1 \psi(r_0) \end{aligned}$$

$\leq r_0$,

$$2\left(\frac{\pi}{p}\right)^{\frac{1}{p}} + \frac{1}{2}r_0 + \left(\frac{1}{4}\right)\left(\frac{1}{3}\right)r_0 \leq r_0.$$

Thus, for the number $r_0 = \left(\frac{24}{5}\right)$

$\times \left(\frac{\pi}{p}\right)^{\frac{1}{p}}$. Hence all the assumptions are satisfied and so, Eq.(3.4) has at least one solution in $L^p(\mathbb{R}^2)$.

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