



## A $q$ -VARIANT OF STEFFENSEN'S METHOD OF FOURTH-ORDER CONVERGENCE

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**Abstract:** Starting from  $q$ -Taylor formula, we suggest a new  $q$ -variant of Steffensen's method of fourth-order convergence for solving non-linear equations.

**Keywords:**  $q$ -Taylor series; Jackson  $q$ -difference operator; Steffensen's method; Nonlinear equations.

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## 1 INTRODUCTION

Finding the zeros of a nonlinear equation,  $f(x) = 0$ , is a classical problem of numerical analysis. Analytic methods for solving such equations rarely exist, and therefore, one can hope to obtain only approximate solutions by relying on iteration methods. For a survey of the most important algorithms, some excellent textbooks are available (see, [4, 8, 10]). The classical Newton's method:

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}, \quad n = 0, 1, 2, \dots \quad (1)$$

Being quadratically convergent, Newton's method is probably the best known and most widely used algorithm. Time to time the method has been derived and modified in a variety of ways. One such method derived from Newton's method by approximating the derivative with non-derivative term of difference quotient is Steffensen's method [9, 11]. The method requires two evaluations of function and is quadratically convergent. The interesting iterative scheme is Steffensen's method that has the following form:

$$x_{n+1} = x_n - \frac{f^2(x_n)}{(f(x_n + f(x_n)) - f(x_n))}, \quad n = 0, 1, 2, \dots \quad (2)$$

In order to control the approximation of the derivative and the stability of the iteration, a Steffensen's type method has been proposed in [2], this approach is based on a better approximation to the derivative  $f'(x_n)$  in each iteration. It has the following form:

$$x_{n+1} = x_n - \frac{f(x_n)}{(f(x_n + \alpha_n |f(x_n)| f(x_n)) - f(x_n))/\alpha_n |f(x_n)| f(x_n))}. \quad (3)$$

After that, the paper [1] has extended the above result on Banach spaces, obtained its local and semi-local convergence theorems, and made its applications on boundary-value problems by multiple shooting methods.

A family of fourth order methods free from any derivative, satisfying the highest convergence order were established in [12, 13].

## 2 $q$ -Calculus

In the following,  $q$  is a positive number,  $0 < q < 1$ . For  $n \in \mathbf{N} = \{0, 1, \dots\}$ ,  $k \in \mathbf{Z}^+ = \{1, 2, \dots\}$  and  $a, a_1, \dots, a_k \in \mathbf{C}$ , the  $q$ -shifted factorial, the multiple  $q$ -shifted factorial and the  $q$ -binomial coefficients are defined by

$$(a; q)_0 := 1, \quad (a; q)_n := \prod_{j=0}^{n-1} (1 - aq^j), \quad (a_1, a_2, \dots, a_k; q)_n := \prod_{j=1}^k (a_j; q)_n, \quad (4)$$

and

$$\begin{bmatrix} a \\ 0 \end{bmatrix}_q := 1, \quad \text{and} \quad \begin{bmatrix} a \\ n \end{bmatrix}_q := \frac{(1 - q^a)(1 - q^{a-1}) \cdots (1 - q^{a-n+1})}{(q; q)_n}, \quad (5)$$

respectively. The limit,  $\lim_{n \rightarrow \infty} (a; q)_n$ , is denoted by  $(a; q)_\infty$ . Moreover  $(a; q)_n$  has the representation, cf. [5],

$$(a; q)_n = \sum_{k=0}^n (-1)^k \begin{bmatrix} n \\ k \end{bmatrix}_q q^{k(k-1)/2} a^k. \quad (6)$$

The  $q$ -Gamma function, [5, 6], is defined by

$$\Gamma_q(z) := \frac{(q; q)_\infty}{(q^z; q)_\infty} (1 - q)^{1-z}, \quad z \in \mathbf{C}, |q| < 1, \quad (7)$$

where we take the principal values of  $q^z$  and  $(1 - q)^{1-z}$ . In particular



$$\Gamma_q(n+1) = \frac{(q; q)_n}{(1-q)^n}, \quad n \in \mathbf{N}.$$

Let  $\mu \in \mathbf{C}$  be fixed. A set  $A \subseteq \mathbf{C}$  is called a  $\mu$ -geometric set if for  $x \in A$ ,  $\mu x \in A$ . Let  $f$  be a function defined on a  $q$ -geometric set  $A \subseteq \mathbf{C}$ . The  $q$ -difference operator is defined by the formula

$$D_q f(x) := \frac{f(x) - f(qx)}{x - qx}, \quad x \in A - \{0\}. \tag{8}$$

If  $0 \in A$ , we say that  $f$  has  $q$ -derivative at zero if the limit

$$\lim_{n \rightarrow \infty} \frac{f(xq^n) - f(0)}{xq^n}, \quad x \in A \tag{9}$$

exists and does not depend on  $x$ . We then denote this limit by  $D_q f(0)$ . The  $q$ -integration of F. H. Jackson [7] is defined for a function  $f$  defined on a  $q$ -geometric set  $A$  to be

$$\int_a^b f(t) d_q t := \int_0^b f(t) d_q t - \int_0^a f(t) d_q t, \quad a, b \in A, \tag{10}$$

where

$$\int_0^x f(t) d_q t := \sum_{n=0}^{\infty} xq^n (1-q) f(xq^n), \quad x \in A, \tag{11}$$

provided that the series converges. A function  $f$  which is defined on a  $q$ -geometric set  $A$ ,  $0 \in A$ , is said to be  $q$ -regular at zero if

$$\lim_{n \rightarrow \infty} f(xq^n) = f(0), \quad \text{for every } x \in A.$$

The rule of  $q$ -integration by parts is

$$\int_0^a g(x) D_q f(x) d_q x = (fg)(a) - \lim_{n \rightarrow \infty} (fg)(aq^n) - \int_0^a D_q g(x) f(qx) d_q x. \tag{12}$$

If  $f, g$  are  $q$ -regular at zero, the  $\lim_{n \rightarrow \infty} (fg)(aq^n)$  on the right hand side of (12) will be replaced by  $(fg)(0)$ . The two variable polynomial  $\varphi_n(x, a)$ ,  $x, a \in \mathbf{C}$ , are defined to be

$$\varphi_0(x, a) := 1, \quad \varphi_n(x, a) := \begin{cases} x^n (a/x; q)_n, & x \neq 0, \\ (-1)^n q^{\frac{n(n-1)}{2}} a^n, & x = 0. \end{cases} \tag{13}$$

In [3], Annaby and Mansour gave  $q$ -Taylor series in the following forms

$$f(x) = \sum_{k=0}^{n-1} \frac{D_q^k f(a)}{\Gamma_q(k+1)} \varphi_k(x, a) + \frac{1}{\Gamma_q(n)} \int_a^x \varphi_{n-1}(x, qt) D_q^n f(t) d_q t. \tag{14}$$

$$f(x) = \sum_{k=0}^{n-1} (-1)^k q^{\frac{k(k-1)}{2}} \frac{D_q^k f(aq^{-k})}{\Gamma_q(k+1)} \varphi_k(a, x) + \frac{1}{\Gamma_q(n)} \int_{aq^{-n+1}}^x \varphi_{n-1}(x, qt) D_q^n f(t) d_q t, \tag{15}$$



### 3 A $q$ -Steffensen-secant method

In the following we set  $e_n = x_n - a$ ,  $e_n^* = y_n - a$ ,  $z_n = x_n + qf(x_n)$ ,  $y_n = x_n - f(x_n)/f[x_n, z_n]$ , where

$$f[a, b] = \frac{f(a) - f(b)}{a - b},$$

$$A = \frac{D_q f(a)}{\Gamma_q(2)} + \frac{a(1-q)D_q^2 f(a)}{\Gamma_q(3)} + \frac{a^2(1-q)^2(1+q)D_q^3 f(a)}{\Gamma_q(4)}, \tag{16}$$

$$B = \frac{D_q^2 f(a)}{\Gamma_q(3)} + \frac{a(1-q)(2+q)D_q^3 f(a)}{\Gamma_q(4)}, \tag{17}$$

and

$$C = \frac{D_q^3 f(a)}{\Gamma_q(4)}. \tag{18}$$

Now, we state and prove our  $q$ -Steffensen-secant Theorem with fourth order convergence.

**Theorem 3.1** Let  $f : D \rightarrow \mathbb{R}$  be a real-valued function with a root  $a \in D$ ,  $D \subset \mathbb{R}$ , and let  $x_0$  be closed enough to  $a$ . If  $D_q^k(x)$ ,  $k=1,2,3$  exist, and  $D_q(a) \neq 0$ , then

$$x_{n+1} = y_n - \frac{f[x_n, y_n] - f[z_n, y_n] + f[z_n, x_n]}{f^2[x_n, y_n]} f(y_n), n \in \mathbb{N}, \tag{19}$$

is fourth-order convergent, and satisfies the following error equation

$$e_{n+1} = A^{-1}B(1+qA)[A^{-1}C(1+qA) - A^{-2}B(3+2qA+2q^2A^2)]e_n^4 + O(e_n^5), n \in \mathbb{N}. \tag{20}$$

**Proof:** Using the Taylor expansion in (14), we have

$$\begin{aligned} f(x_n) = & \frac{D_q f(a)}{\Gamma_q(2)}(x_n - a) + \frac{D_q^2 f(a)}{\Gamma_q(3)}(x_n - a)(x_n - qa) + \\ & \frac{D_q^3 f(a)}{\Gamma_q(4)}(x_n - a)(x_n - qa)(x_n - q^2a) + \frac{1}{\Gamma_q(4)} \int_a^{x_n} \varphi_3(a, qt) D_q^4 f(t) d_q t. \end{aligned} \tag{21}$$



Rearranging the above equation again gives:

$$f(x_n) = Ae_n + Be_n^2 + Ce_n^3 + O(e_n^4), \tag{22}$$

$f(z_n) = f(x_n + qf(x_n)) =$

$$\begin{aligned} & \frac{1}{\Gamma_q(4)} \int_a^{x_n + qf(x_n)} \varphi_3(a, qt) D_q^4 f(t) d_q t + \frac{D_q f(a)}{\Gamma_q(2)} (x_n - a + qf(x_n)) \\ & + \frac{D_q^2 f(a)}{\Gamma_q(3)} (x_n - a + qf(x_n))(x_n - qa + qf(x_n)) + \\ & \frac{D_q^3 f(a)}{\Gamma_q(4)} (x_n - a + qf(x_n))(x_n - qa + qf(x_n))(x_n - q^2 a + qf(x_n)) \\ \text{that is} \quad & = O(e_n^4) + \frac{D_q f(a)}{\Gamma_q(2)} (e_n + qf(x_n)) \\ & + \frac{D_q^2 f(a)}{\Gamma_q(3)} (e_n + qf(x_n))(e_n + qf(x_n) + a(1-q)) + \\ & \frac{D_q^3 f(a)}{\Gamma_q(4)} (e_n + qf(x_n))(e_n + qf(x_n) + a(1-q))(e_n + qf(x_n) + a(1-q^2)) \\ & = A(e_n + qf(x_n)) + B(e_n + qf(x_n))^2 + C(e_n + qf(x_n))^3 + O(e_n^4). \end{aligned} \tag{23}$$

Thus,

$$\begin{aligned} f(z_n) = & A[1 + qA]e_n + B[1 + 3qA + q^2 A^2]e_n^2 + \\ & [C[1 + 4qA + 3q^2 A^2 + q^3 A^3] + 2qB^2[1 + qA]]e_n^3 + O(e_n^4). \end{aligned} \tag{24}$$

Moreover,

$$\begin{aligned} f[z_n, x_n] &= \frac{f(x_n + qf(x_n)) - f(x_n)}{qf(x_n)} \\ &= A + B[2 + qA]e_n + [C[3 + 3qA + q^2 A^2] + qB^2]e_n^2 + O(e_n^3). \end{aligned} \tag{25}$$

Therefore,



$$g(x_n) := \frac{f(x_n)}{f[z_n, x_n]} = O(e_n^4) + e_n - A^{-1}B[1 + qA]e_n^2 + [A^{-2}B^2[1 + qA][2 + qA] - qA^{-1}B^2 - A^{-1}C[2 + 3qA + q^2A^2]]e_n^3. \tag{26}$$

Consequently,

$$\begin{aligned} f(y_n) &= f(x_n - g(x_n)) = \frac{D_q f(a)}{\Gamma_q(2)}(x_n - a - g(x_n)) + \frac{D_q^2 f(a)}{\Gamma_q(3)}(x_n - a - g(x_n))(x_n - qa - g(x_n)) \\ &+ \frac{D_q^3 f(a)}{\Gamma_q(4)}(x_n - a - g(x_n))(x_n - qa - g(x_n))(x_n - q^2a - g(x_n)) \\ &+ \frac{1}{\Gamma_q(4)} \int_a^{x_n - g(x_n)} \varphi_3(a, qt) D_q^4 f(t) d_q t \\ &= O(e_n^4) + \frac{D_q f(a)}{\Gamma_q(2)}(e_n - g(x_n)) + \frac{D_q^2 f(a)}{\Gamma_q(3)}(e_n - g(x_n))(e_n + qf(x_n) + a(1 - q)) + \\ &\frac{D_q^3 f(a)}{\Gamma_q(4)}(e_n - g(x_n))(e_n - g(x_n) + a(1 - q))(e_n - g(x_n) + a(1 - q^2)) \\ &= A(e_n - g(x_n)) + B(e_n - g(x_n))^2 + C(e_n - g(x_n))^3 + O(e_n^4). \end{aligned} \tag{27}$$

This means

$$f(y_n) = O(e_n^4) + B[1 + qA]e_n^2 - [A^{-1}B^2[1 + qA][2 + qA] - qB^2 - C[2 + 3qA + q^2A^2]]e_n^3, \tag{28}$$

and

$$e_n^* = O(e_n^4) + A^{-1}B[1 + qA]e_n^2 - [A^{-2}B^2[1 + qA][2 + qA] - qA^{-1}B^2 - A^{-1}C[2 + 3qA + q^2A^2]]e_n^3. \tag{29}$$

On the other hand

$$\begin{aligned} f[x_n, y_n] &= \frac{f(x_n) - f(y_n)}{g(x_n)} \\ &= A + Be_n + [C + A^{-1}B^2[1 + qA]]e_n^2 + O(e_n^3). \end{aligned} \tag{30}$$

Hence

$$\begin{aligned} f^2[x_n, y_n] &= O(e_n^4) + A^2 + 2ABe_n + [2AC + B^2[3 + 2qA]]e_n^2 + [2BC + 2A^{-1}B^3[1 + qA]]e_n^3. \end{aligned} \tag{31}$$

But

$$\begin{aligned} f[z_n, y_n] &= \frac{f(z_n) - f(y_n)}{qf(x_n) + g(x_n)} = A + B(1 + qA)e_n + [C(1 + qA)^2 + A^{-1}B^2(1 + 4qA + 2qA^2)]e_n^2 + O(e_n^3). \end{aligned} \tag{32}$$



So that

$$H(x_n) = \frac{f[y_n, x_n] - f[z_n, y_n] + f[z_n, x_n]}{f^2[y_n, x_n]} = A^{-1} + [A^{-2}C(1+qA) - A^{-3}B(3+2qA+2q^2A^2)]e_n^2 + [-2A^{-3}BC(2+qA) + A^{-4}B^2(5+3qA+4q^2A^2)]e_n^3 + O(e_n^4). \quad (33)$$

If we multiply  $H(x_n)$  by  $f(y_n)$  we get

$$H(x_n)f(y_n) = H(x_n)f[y_n, a]e_n^* = [1 + [A^{-1}C(1+qA) - A^{-2}B(3+2qA+2q^2A^2)]e_n^2 + [-2A^{-2}BC(2+qA) + A^{-3}B^2(5+3qA+4q^2A^2)]e_n^3 + O(e_n^4)]e_n^*. \quad (34)$$

Taking in consideration that  $x_{n+1}$  is nothing but  $y_n - H(x_n)f(y_n)$  we get

$$x_{n+1} = y_n - H(x_n)f(y_n) = x_n - [1 + [A^{-1}C(1+qA) - A^{-2}B(3+2qA+2q^2A^2)]e_n^2 + [-2A^{-2}BC(2+qA) + A^{-3}B^2(5+3qA+4q^2A^2)]e_n^3 + O(e_n^4)]e_n^*. \quad (35)$$

Thus

$$e_{n+1} = [A^{-1}C(1+qA) - A^{-2}B(3+2qA+2q^2A^2) + O(e_n)]e_n^2 e_n^* = A^{-1}B[1+qA][A^{-1}C(1+qA) - A^{-2}B(3+2qA+2q^2A^2)]e_n^4 + O(e_n^5). \quad (36)$$

This completes the proof.

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